

Please cancel claim 1, add claim 25, and amend the remaining claims as follows:

In The Claims

1. (Canceled)
2. (Currently Amended) The [R]robot according to [C]claim [1, characterised in that] 25, wherein adjacent members [(4)] are linked in form-fitting manner to each other.
3. (Currently Amended) The [R]robot according to [C]claim [1 or 2, characterised in that] 25, wherein at least two adjacent members [(4)] are linked to each other by a ball joint.
4. (Currently Amended) The [R]robot according to [C]claim [1, 2 or 3, characterised in that means are provided through which the] 25, and further comprising a spatial deflection [is limited] limiting mechanism.
5. (Currently Amended) The [R]robot according to [C]claim 4, [characterised in that the means] wherein the spatial deflection limiting mechanism comprises at least one stop connected to a first member and at least one counterstop connected to a second member disposed adjacent to the first member.
6. (Currently Amended) The [R]robot according to [C]claim 5, [characterised in that the] wherein at least one stop is formed by a projection [(14)] directed radially outwards, said projection engaging in a recess [(15)] on an adjacent member to limit spatial deflection.
7. (Currently Amended) The [R]robot according to [C]claim 6, [characterised in that the] wherein at least one projection [(14)] is formed on [the] a joint body [(12)] and the recess [(15)] is formed in [the] a joint socket [(13)].
8. (Currently Amended) The [R]robot according to [C]claim 6 [or 7, characterised in that] wherein the stop comprises at least two projections [(14) are provided,] joined to a member and arranged substantially equidistant from each other.

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9. (Currently Amended) The [R]robot according to one of the claim[s 1 to 8,
characterised in that] 25, wherein the central body [(5) is provided with] comprises at least one
web [(8)] linked to a wall [(7)], whereby the wall [(7)] and the central body [(5) delimit a] define
the channel [(9)].

10. (Currently Amended) The [R]robot according to [C]claim 9, [characterised in that]
wherein the [wall (7)] has at least one gap [(10)] extending in the longitudinal direction of the
central body [(5)].

11. (Currently Amended) The [R]robot according to [C]claim 9 [or 10, characterised in
that] wherein [the wall (7) is so designed that] sections [(17, 20)] of the walls [(7)] of two
adjacent members [(4)] overlap each other.

12. (Currently Amended) The [R]robot according to [one of the claims 1 to 11
characterised in that] claim 25 and further comprising holders [(2) are provided by means of
which the] attaching the conductor guiding apparatus [(1) is attached] to [said] the robot.

13. (Currently Amended) The [R]robot according to [C]claim 12, [characterised in that]
wherein the holders [(2) are designed clamp-shaped, whereby said holder interacts with] are
clamps that are shaped for securing the wall [(7)] of a member [(4)].

14. (Currently Amended) The [R]robot according to [C]claim 12 [or 13, characterised in
that] wherein the holder [(2)] is linked to a member in a form-fitting [or force-fitting] manner.

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15. (Currently Amended) The [R]robot [with at least one conductor guiding apparatus

(1) running at least partially on the outside, in which guiding apparatus conductors (3), hoses or similar are guided, in particular] according to [one of the claims 1 to 14] of claim 25, [having] and further comprising an apparatus [(30)] for guiding and [storage of] storing the conductor guiding apparatus in [the base (29) of] the robot, [characterised in that] wherein the apparatus [(30)] has a guiding region [(31)] formed in a first plane and a storage region [(32)] formed in a second plane, and the second plane is formed separately from the first plane.

16. (Currently Amended) The [R]robot according to [C]claim 15, [characterised in that] wherein the guiding region [(31)] lies in a substantially horizontal plane.

17. (Currently Amended) The [R]robot according to [C]claim 15 [or 16, characterised in that] wherein the first and second planes lie at an angle of up to 90° to each other.

18. (Currently Amended) The [R]robot according to [C]claim 15 [, 16 or 17, characterised in that] wherein the storage region [(32)] lies in a substantially vertical plane.

19. (Currently Amended) The [R]robot according to [one of the] claim[s] 15 [to 18, characterised in that] wherein the guiding region [(31)] is designed in the form of] defines a channel.

20. (Currently Amended) The [R]robot according to [one of the claims] claim 15 [to 19, characterised in that] wherein the guiding region [(31)] is designed] is arc-shaped [and, in particular, in the form of a partial circle, preferably annular].

21. (Currently Amended) The [R]robot according to [one of the claims] claim 15 [to 20, characterised in that] wherein the storage region [(32)] is so designed that] receives the conductor guiding apparatus [(1) forms] to define an upper strand and a lower strand in the storage region [(32)].

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22. (Currently Amended) The [R]robot according to [one of the claims] claim 15 [to 21, characterised in that] wherein the guiding region [(31)] and the storage region [(32)] are detachably linked to each other.

23. (Currently Amended) The [R]robot according to [one of the claims] claim 15 [to 22, characterised in that between] wherein the guiding region [(31)] and the storage region [(32),] have disposed there between a transition region [(33) is provided].

24. (Currently Amended) The [R]robot according to [one of the claims] claim 15 [to 23, characterised in that] wherein the guiding region [(31)], the storage region [(32) and/or] or the transition region [(33) are designed] are at least partially [as] formed as molded parts [and, in particular, as sheet metal formed parts].

Please add the following new claim:

25. (New) A robot having a conductor guiding apparatus for guiding conductors, hoses and the like, the conductor guiding apparatus comprising:
a plurality of members, each member having a central body and defining a conductor channel; and
a flexible linking element extending through the central body of the members to join the members together for movement relative to one another.